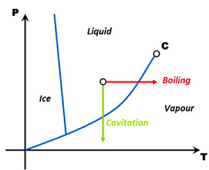


Experimental analysis of cavitation instabilities on spatial inducer

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1 - Overview

• Cavitation

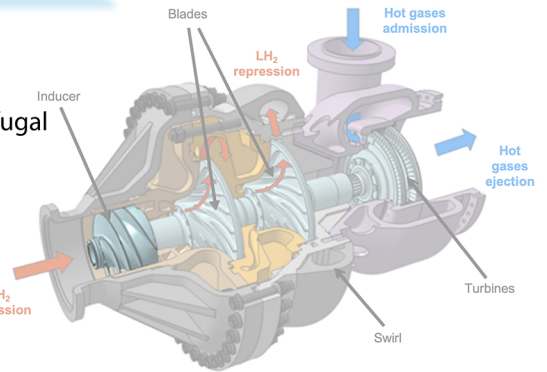


• Risks

- Performance drop
- Erosion
- Instabilities
- POGO
- Overspeed

• Inducer aims

- First overspressure
- Avoid cavitation in centrifugal
- Allow low inlet operating



Objective:

Build some tools to identify cavitating regime dynamics and the impact on the launcher (efforts, vibrations, performance, ...)

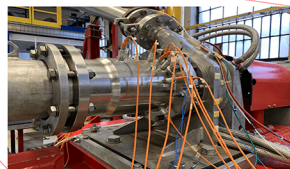
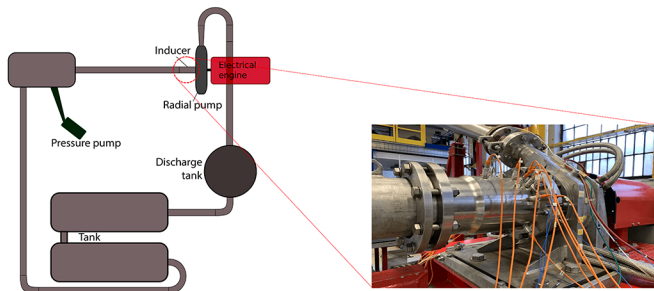
2 - Test-rig (SESAME)

Closed loop of water driven by an electrical engine (200 kW)

- Temperature
- Acceleration
- Flow rate
- Pressure (unsteady) at the carter
- Force / moment (rotating frame)

Sampling rate:
2048Hz

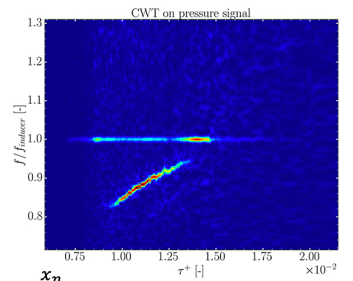
Similitude laws to know the hydrogen behaviour



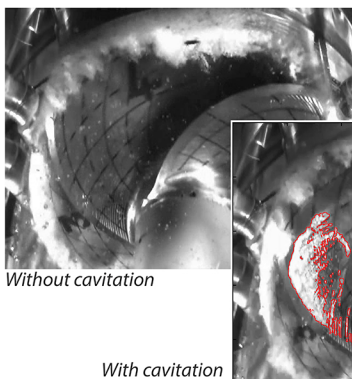
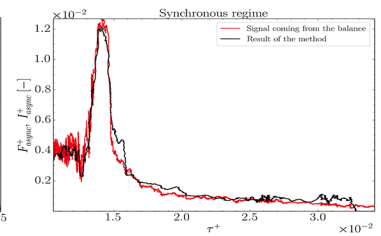
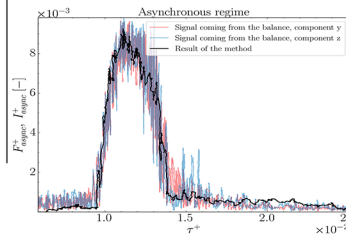
3 - Radial efforts estimation

Quantification of **radial efforts** on the shaft's turbopump

Pressure signals - $P(\tau)$
↓
Continuous Wavelet Transform
↓
Denoising
↓
Inverse Continuous Wavelet Transform - $P'(\tau)$



$$I_{async}, I_{sync}(\tau) = \pi R \int_{x_1}^{x_n} P'(\tau) \cdot \Delta x dx$$



Contours detection with stroboscopic light and camera.

Estimation of the cavitation surface.

• Visualization test campaign with **high speed camera**

4 - Perspectives

- Improvement of forces estimation method
- Understand phenomenon behavior using **Cross Wavelet Analysis**

